

**CHAPTER ONE: BASIC PRINCIPLES**

1. **There are essentially two ways of explaining the fundamentals of MRI: the classical theory also called Newtonian and via:**  
A quantum physics                      B mechanics theory                      C quantum mechanics                      D mass theory
2. **----- are two or more atoms arranged together.**  
A Molecules                      B Protons                      C Electrons                      D Nucleons
3. **----- is the most abundant atom in the human body.**  
A Water                      B Carbon                      C Oxygen                      D Hydrogen
4. **The atom consists of a central nucleus and orbiting:**  
A molecules                      B protons                      C electrons                      D nucleons
5. **The ----- gives an atom its chemical identity.**  
A mass number                      B atomic number                      C type of molecules                      D number of protons
6. **Atoms of elements with the same number of protons but a different number of neutrons are called isotopes.**  
A True                      B False
7. **Some of the particles in the atom possess an electrical charge, protons have:**  
A variable electrical charge                      B negative electrical charge                      C no electrical charge                      D positive electrical charge
8. **Ionization occurs when energy knocks protons out from the atom and causes electrical instability.**  
A True                      B False
9. **The proton consists of ----- spinning quarks.**  
A 1                      B 2                      C 3                      D 4
10. **B0 refers to the large magnetic field of the MRI scanner and it is measured in:**  
A Teslas                      B Hounsfield                      C Boltzmann                      D Net magnetic vector
11. **The speed at which each hydrogen nucleus precess around B0 is called:**  
A net magnetic vector                      B signal to noise ratio                      C larmor frequency                      D lambda frequency
12. **The unit of precessional frequency is:**  
A Teslas                      B Hertz                      C Hounsfield                      D quartz
13. **----- means that magnetic moments of hydrogen are at different places on the precessional path at a moment in time.**  
A In phase                      B Radian                      C Coherent                      D Out of phase
14. **----- is caused when the spins are unable to absorb more energy or to be stimulated and release more energy.**  
A Saturation                      B Flip angle                      C Radiofrequency                      D Amplitude
15. **The change of magnetic flux through a closed circuit induces a(n) ----- in the circuit.**  
A Radiofrequency                      B Electromotive force                      C Ionization                      D Tesla
16. **The signal is produced when coherent magnetization cuts across the coil.**  
A True                      B False
17. **----- is the time from the application of the RF excitation pulse to the peak of signal induced in the receiver coil.**  
A Receiver coil                      B Electromotive                      C Echo-time                      D Repetition-time

18. The TR thus determines the amount of ——— relaxation that has occurred when signal is read.

- A Gradient-echo                      B T1                                      C T2                                      D Proton density

## CHAPTER TWO: IMAGE WEIGHTING AND CONTRAST

19. ——— contrast parameters are those that cannot be changed because they are inherent to the body's tissues.

- A Longitudinal                      B Extrinsic                              C Parallel                              D Intrinsic

20. This is an extrinsic contrast parameter:

- A Proton density                      B ACD                                      C Flip angle                              D T1 recovery time

21. T2 decay occurs 5–10 times faster than T1 recovery.

- A True                                      B False

22. ——— is caused by hydrogen nuclei giving up their energy to the surrounding environment or molecular lattice.

- A T2 recovery                      B T1 recovery                              C T2 decay                              D T1 decay

23. T1 recovery is the time it takes for——— of the longitudinal magnetization to recover in a tissue.

- A 50%                                      B 37%                                      C 90%                                      D 63%

24. The echo time (TE) therefore determines how much T2 decay occurs in a tissue when signal is collected.

- A True                                      B False

25. The ——— of a tissue is the number of mobile hydrogen protons per unit volume of that tissue.

- A T2                                      B ACD                                      C proton density                              D T1 recovery time

26. Fat has a low signal and is hypointense.

- A True                                      B False

27. ——— are used to show anatomy and pathology after administration of a contrast agent.

- A Proton density                      B Long TR                                      C T1-weighted images                      D T2-weighted images

28. ——— has low signal on T1-weighted images.

- A Fat                                      B Intraosseous lipoma                      C Cyst with proteinaceous                      D Avascular necrosis

29. ——— has low signal on T2-weighted images.

- A Inflammation                      B Bone island                                      C Water                                      D Hemangioma

30. ——— is a term used to describe the movement of molecules in the extracellular space due to random thermal motion.

- A Diffusion                                      B ADC                                      C Proton density                                      D Susceptibility-weighted

31. In areas of restricted diffusion, the ADC is high because the extracellular space is small.

- A True                                      B False

32. The b value is an intrinsic contrast parameter that controls how much the intrinsic ADC influences image contrast.

- A True                                      B False

33. ——— uses the magnetic susceptibility differences between tissues to generate image contrast.

- A DWI                                      B ADC                                      C SWI                                      D BOLD

34. The most commonly used contrast agent on MRI is:

- A Pentolinium                      B Barium                                      C Iodine                                      D Gadolinium



52. STIR is an extremely important sequence in ——— imaging.  
 A neurological                      B musculoskeletal                      C abdominal                      D pelvic
53. STIR should be used in conjunction with contrast agents to enhance the structures.  
 A True                      B False
54. ——— is used to suppress high CSF signal in T2 weighted images so that the pathology adjacent.  
 A DWI                      B STIR                      C T1-weighted                      D FLAIR
55. FLAIR is an extremely important sequence in ——— imaging.  
 A neurological                      B musculoskeletal                      C abdominal                      D pelvic
56. One of the advantages of inversion recovery sequences is their short scan-time.  
 A True                      B False
57. Triple IR prep adds a further inverting pulse at the T1 of fat to null fat and blood together, it is useful when determining fatty infiltration of:  
 A the pancreas                      B breast tissue                      C heart walls                      D the liver
58. ——— determines the number of k-space lines filled every TR, it controls how many RF rephasing pulses are applied every TR.  
 A inversion time                      B Tau                      C half echo train                      D echo train length

## CHAPTER FOUR: GRADIENT-ECHO PULSE SEQUENCES

59. Gradient echo pulse sequences use ——— rather than RF pulses to rephase the magnetic moments of hydrogen nuclei to form an echo.  
 A pulses                      B gradients                      C inversion                      D angles
60. Gradient echo pulse sequence has shorter scan times.  
 A True                      B False
61. The process of dephasing magnetic moments with gradients is called:  
 A inverse gradients                      B flip angles                      C gradient spoiling                      D tau
62. Whether gradient field adds or subtracts from the main magnetic field depends on the direction of current that passes through the gradient coils, this is called:  
 A flip angles                      B gradient swiffer                      C gradient spoiling                      D polarity of the gradient
63. Gradient-echoes are created by a ———, this means that it consists of two lobes, one negative and one positive.  
 A inverse pulses                      B bipolar gradient                      C inversion time                      D flip angles
64. Gradient-echo sequences use gradients to rephase the magnetic moments of hydrogen nuclei and usually flip angles less than:  
 A 90°                      B 60°                      C 180°                      D 0°
65. In gradient echo pulse sequence less time is required for relaxation, this is why a long TR can be used.  
 A True                      B False
66. Magnetic susceptibility artifacts increase in gradient echo pulse sequences because inhomogeneities are not compensated.  
 A True                      B False
67. In G-echo pulse sequences T2 is termed ——— to reflect the fact that magnetic field inhomogeneities are not compensated.  
 A T1\*                      B T2 GRE                      C T2\*                      D T1 GRE
68. In gradient-echo pulse sequences, the TR and the ——— control the amount of T1 relaxation and saturation that occurs.  
 A T2\*                      B Tau                      C gradient spoiling                      D flip angle



86. ——— is a rapid acquisition technique that begins with a sequence of one or more RF pulses and is followed by a series of gradient-echoes.
- A Spoiled gradient echo      B balanced gradient-echo      C echo planar imaging      D incoherent pulse sequences
87. EPI pulse sequence decreases physiological motion in MR images, which is advantageous when imaging the ——— and when performing interventional techniques.
- A heart      B stomach      C lung      D liver
88. Blurring is an artifact that occurs as a result of T1 recovery times during the acquisition.
- A True      B False
89. ——— determines how much phase shift there is across an area of tissue per s in DWI.
- A Flip angle      B TE      C TR      D b value

## CHAPTER FIVE: SPATIAL ENCODING

90. The middle of the axis of the gradient remains at the field strength of the main magnetic field even when the gradient is switched on, this is called:
- A magnetic isocenter      B polarity      C gradient coils      D echo planar imaging
91. ——— is commonly used to denote magnetic field strength or magnetic flux density using the SI system.
- A Gauss      B Tesla      C Coulombs      D Homs
92. Gradient amplitude determines the rate of change of the magnetic field strength along the gradient axis.
- A True      B False
93. ——— are conductors that cause a linear change in the magnetic field strength along their axes when a current is passed through them.
- A Isocenter      B Magnetic moment      C Gradient coils      D Gradient amplitude
94. ——— alters the magnetic field strength along the vertical axis of the magnet (from the back to the front of the patient).
- A z gradient      B x gradient      C t gradient      D y gradient
95. To achieve ———, a shallow slice-select slope and/or broad transmit bandwidth is applied.
- A thin slices      B thick slices
96. Slice thickness is altered by changing the slope of the slice-select gradient and the:
- A polarity      B amplitude      C transmit bandwidth      D magnetic moment
97. Once a slice is selected, signal coming from it is located along both axes of the image, the signal is usually located along the long axis of the anatomy by a process known as:
- A RF excitation      B carrier frequency      C transmit bandwidth      D frequency encoding
98. In ——— the long axis of the anatomy usually lies along the horizontal axis of the magnet (left to right of the patient), and, therefore, the x gradient performs frequency encoding.
- A axial images      B coronal images      C sagittal images      D neutral images
99. To achieve a ——— in the frequency direction, a shallow frequency-encoding gradient is applied.
- A large FOV      B small FOV
100. To achieve a ———, the phase-encoding gradient is applied many times during the pulse sequence.
- A low phase matrix      B high phase matrix

## CHAPTER SIX: K-SPACE

101. The phase shift caused by the phase-encoding gradient creates a:
- A single spin      B spatial encoding      C spin-echo sequence      D spatial frequency

102. The ——— of K-space is horizontal and is centered in the middle of several horizontal lines.  
 A phase axis                      B frequency                      C spatial frequencies                      D spatial encoding
103. The slice-select gradient is not applied during the RF excitation and rephase pulses to selectively excite and rephase a slice.  
 A True                      B False
104. A few preliminary steps are needed to ensure that the data are in a format required for FFT mathematics to create an image of slice. The first step is to simplify the frequencies and amplitudes present in the echo. This step is called:  
 A frequency encoding                      B readout or measurement gradient                      C frequency and amplitude modulation                      D sampling time
105. The number of data points in each line of k-space depends on the frequency matrix.  
 A True                      B False
106. The digital sampling frequency determines the time interval between each data point, this time interval is called the sampling interval and is calculated by dividing the digital sampling frequency by 1.5.  
 A True                      B False
107. The bandwidth used in the ——— to excite a slice is called the transmit bandwidth.  
 A range of frequencies                      B low-frequency                      C RF excitation pulse                      D phase-encoding
108. The digital sampling frequency is a parameter directly selected in the scan protocol.  
 A True                      B False
109. The minimum TE is affected by the duration of the sampling window because the echo is not centered in middle of the time window.  
 A True                      B False
110. ——— is required to mathematically "unlock" these data so that the system can locate a signal at each pixel location in the slice and assign a signal intensity to it.  
 A FFT                      B FOV                      C TR                      D PE
111. The ——— of k-space are filled using shallow phase-encoding gradient slopes.  
 A outer lines                      B superior lines                      C low lines                      D central lines
112. The outer portion of k-space contains data that have low signal amplitude and high resolution.  
 A True                      B False
113. When the system calculates the scan time, it usually multiplies the following three parameters: TR, ——— and Number of signal averages (NSA).  
 A Phase axis                      B FFT                      C Phase matrix                      D spatial encoding
114. Partial echo is performed when only part of the echo is read during application of the:  
 A sequential and 3D acquisition                      B frequency-encoding gradient                      C polarity of the phase                      D RF excitation pulse
115. A ——— is a good screening radiograph for most dentoalveolar trauma.  
 A panorex                      B panrad                      C panphoton                      D panoria
- CHAPTER SEVEN: PROTOCOL OPTIMIZATION**
116. The ——— is defined as the ratio of the amplitude of signal received to the average amplitude of the background noise.  
 A contrast-to-noise ratio (CNR)                      B High spatial resolution                      C signal-to-noise ratio (SNR)                      D scan time
117. Noise represents frequencies that exist randomly in space and time.  
 A True                      B False











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